

Appl. No. 10/615,635  
Supplemental Amdt. dated August 8, 2005

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (Currently amended) A position location device comprising:  
a waterproof housing;  
a processor enclosed within the waterproof housing;  
a global positioning system receiver enclosed within the waterproof housing and connected to the processor; and  
a pressure transducer connected to the processor;  
clock circuitry connected to the processor and enclosed within the waterproof housing;  
wherein the global positioning system receiver includes an antenna enclosed within the waterproof housing; and  
wherein the pressure transducer is configured to measure depth under water;  
wherein the processor is configured to obtain at least one measurement of position using the global positioning system when the position location device is above water;  
wherein the processor is configured to obtain at least one measurement of depth and time using the pressure transducer and the clock circuitry when the location device is submerged;  
wherein the processor is configured to record a profile of the dive including the measurements of multiple positions and multiple depths and times.
2. (Cancelled)
3. (Currently amended) The position location device of claim 1, further comprising:  
~~clock circuitry connected to the processor and enclosed within the waterproof housing; and~~

**Appl. No. 10/615,635  
Supplemental Amdt. dated August 8, 2005**

memory connected to the processor and enclosed within the waterproof housing; and  
at least one input/output device connected to the processor.

4. (Original) The position location device of claim 3, wherein one of the input/output devices is a microphone.

5. (Currently amended) The position location device of claim 3, wherein one of the input/output devices is a keypad including at least one button.

6. (Original) The position location device of claim 1, further comprising:  
a flow meter connected to the processor; and  
a compass connected to the processor.

7. (Previously presented) The position location device of claim 6, wherein the flow meter is an impeller.

8. (Cancelled)

9. (Previously presented) The position location device of claim 6, further comprising:  
a second pressure transducer in communication with the processor; and  
wherein the pressure transducer is configured to generate a signal indicative of air pressure within an air tank.

10. (Original) The position location device of claim 1, further comprising a digital camera connected to the processor.

11. (Currently amended) A position location device comprising:  
means for measuring latitude and longitude;  
means for measuring depth underwater;  
means for measuring time; and  
~~means for recording measurements of latitude, longitude, depth and time;~~

Appl. No. 10/615,635  
Supplemental Amdt. dated August 8, 2005

means for recording multiple measurements of latitude, longitude and time when the position location device is above water;

means for recording multiple measurements of depth and time when the position location device is submerged;

means for generating a dive profile using the recorded measurements;  
and

wherein the means for measuring latitude and longitude, the means for measuring time and the means for recording measurements are enclosed within a waterproof housing.

12. (Original) The position location device of claim 11, further comprising means for annotating recorded measurements of latitude, longitude, depth or time.

13. (Original) The position location device of claim 11, further comprising means for identifying a particular measurement of latitude, longitude, depth or time as being associated with a particular point of interest.

14. (Original) The position location device of claim 11, wherein the time includes information concerning day, month and year.

15. (Original) The position location device of claim 11, further comprising:  
means for measuring water speed; and  
means for measuring bearing.

16. (Previously presented) The position location device of claim 11, further comprising means for measuring air time remaining.

17-23 (Cancelled)

24. (Previously presented) A method of recording data, comprising:  
performing a first measurement of latitude, longitude and time;  
recording information indicative of the first measurement of latitude, longitude and time in a memory;  
descending underwater;

**Appl. No. 10/615,635  
Supplemental Amdt. dated August 8, 2005**

measuring depth and time;  
recording information indicative of the depth and time measurements in the memory;  
resurfacing;  
performing a second measurement of latitude, longitude and time;  
recording information indicative of the second measurement of latitude, longitude and time in the memory; and  
constructing a dive profile using information including the latitude, longitude and time recordings obtained when the diver is at the surface and the depth and time measurements obtained when the diver is underwater.

25-26 (Cancelled)

27. (Previously presented) The method of claim 25, further comprising identifying a particular measurement of latitude, longitude and time or measurement of depth and time as being associated with a particular point of interest.

28. (Previously presented) The method of claim 27, further comprising recording descriptive information that is associated with the identified measurement of latitude, longitude and time or measurement of depth and time.

29. (Original) The method of claim 28, wherein recording descriptive information involves recording signals indicative of speech.

30. (Original) The method of claim 24, wherein the time includes information concerning day, month and year.

31. (Original) The method of claim 24, wherein:  
the measurements of latitude, longitude and time are made using a global positioning system receiver adapted to be taken below the surface of the water; and  
the measurements of depth are made using a pressure transducer.

32. (Original) The method of claim 24, further comprising periodically measuring water speed and bearing.

**Appl. No. 10/615,635**  
**Supplemental Amdt. dated August 8, 2005**

33. (Currently amended) The method of claim 32, further comprising:  
measuring average speed;  
measuring air time remaining; and  
~~estimate~~estimating range based on average speed and air time remaining  
calculations.

34. (Cancelled)

35. (Previously presented) The position location device of claim 10, wherein  
the digital camera includes an electronic flash.

36. (Previously presented) The position location device of claim 1, wherein the  
processor is configured to create a dive log including the recorded dive profile.

37. (Previously presented) The position location device of claim 36, wherein  
the processor is configured to include audio recordings in the dive log.

38. (Previously presented) The position location device of claim 36, wherein  
the processor is configured to include digital photographs in the dive log.

39. (Currently amended) The position location device of claim 1, further  
comprising:  
a sensor connected to the processor;  
wherein the sensor and processor are configured to ~~measuring~~ measure  
speed through water.

40. (Previously presented) The method of claim 24, further comprising  
constructing a dive log including the dive profile.

41. (Previously presented) The method of claim 39, further comprising  
including audio recordings in the dive log.

**Appl. No. 10/615,635**  
**Supplemental Amdt. dated August 8, 2005**

42. (Previously presented) The method of claim 39, further comprising including at least one digital photograph in the dive log.

43. (New) The method of claim 24, wherein the memory is located within a portable device that includes a waterproof casing.

44. (New) The position location device of claim 1, wherein the processor is configured to recognize speech captured using the microphone.